

FUSION2021

Tuesday, 2 November 2021

P14 Information Fusion for Automotive Applications - Zoom link: <https://zoom.us/j/95269868565>, Venue: Zebe & Sena (13:10 - 14:50)

-Conveners: Martin Fritzsche

time	[id] title	presenter
13:10	[34] RadarScenes: A Real-World Radar Point Cloud Data Set for Automotive Applications	SCHUMANN, Ole
13:30	[35] State Estimation of Articulated Vehicles Using Deformed Superellipses	GIEFER, Lino
13:50	[36] An IMM-enabled Adaptive 3D Multi-Object Tracker for Autonomous Driving	LIU, Pengchao
14:10	[37] Improved Virtual Landmark Approximation for Belief Space Planning	NORDLÖF, Jonas
14:30	[38] Observability Analysis of Multipath Assisted Target Tracking with Unknown Reflection Surface	BALACHANDRAN, Aranee