



# FUSION2021

## Wednesday, 3 November 2021

**SS9 Advanced Non-Linear Filtering - 3** - Zoom link: <https://zoom.us/j/94526228977>, Venue: Lupata (10:30 - 12:10)

-Conveners: Jindřich Dunik

time	[id] title	presenter
10:30	[100] Robust Linearly Constrained Filtering for GNSS Position and Attitude Estimation under Antenna Baseline Mismatch	CHAUCHAT, Paul
10:50	[101] Recursive LMMSE Sequential Fusion with Multi-Radar Measurements for Target Tracking	ZHANG, Donglin
11:10	[102] On Tracking Closely-Spaced Targets in a PARAFAC Representation of the Fermionic Wave Function Formulation	GEHLEN, Joshua
11:30	[103] Cooperative Unscented Kalman Filter with Bank of Scaling Parameter Values	DUNIK, Jindrich