

FUSION2021

Wednesday, 3 November 2021

P7 Navigation and Mapping - Zoom link: <https://zoom.us/j/92844812259>, Venue: Sofala (15:20 - 17:00)

-Conveners: Molahlegi Molope

time	[id] title	presenter
15:20	[135] Laplace Particle Filter on Lie Groups Applied to Angles-Only Navigation	CHAHBAZIAN, Clément
15:40	[136] Resilient Collaborative All-Source Navigation	GIPSON, Jonathon
16:00	[137] Filtering and Sensor Optimization Applied to Angles-only Navigation	CHAHBAZIAN, Clément
16:20	[138] Bathymetry and Atomic Gravimetry Sensor Fusion for Autonomous Underwater Vehicle	PALMIER, Camille
16:40	[139] 2D LiDAR and Camera Fusion Using Motion Cues for Indoor Layout Estimation	LI, Jieyu