

FUSION2021

Thursday, 4 November 2021

SS7 Realtime Critical Perception Tasks in the Context of Automated Driving - 1 - Zoom link:

<https://zoom.us/j/98045255521>, Venue: Lupata (13:10 - 14:50)

-Conveners: Frank Bieder

time	[id] title	presenter
13:10	[104] Fast and Robust Ground Surface Estimation from LiDAR Measurements using Uniform B-Splines	RÖSCH, Kevin
13:30	[105] Improving Lidar-Based Semantic Segmentation of TopView Grid Maps by Learning Features in Complementary Representations	BIEDER, Frank
13:50	[106] Pedestrian Detection by Fusion of RGB and Infrared Images in Low-Light Environment	DENG, Qing
14:10	[107] Monocular 3D Multi-Object Tracking with an EKF Approach for Long-Term Stable Tracks	REICH, Andreas